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ABSTRACT OF THE DISCLOSURE

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The invention relates to a surgical instrument with a tool which is located at the distal instrument end, with a stationary first grip part at the proximal instrument end, with a second grip part adjustable in an axially guided manner, in the form of a reel and with an actuation element for the tool, wherein the actuation element in connection with the second grip part is axially adjustable on adjustment of the second grip part. For improving the handling of the instrument according to the invention it is envisaged that by way of a lever system linked onto the second grip part and a stationary part of the instrument the adjustment path of the second grip part is geared down and the force exerted onto the second grip part transmittable, geared up, to the actuation element.

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